

Wellington City LiDAR Index Tiles (2019-2020)

```
Metadata
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  Language
     eng
  Character Set
     Character Set Code
       utf8
  Hierarchy Level
     Scope Code
       dataset
  Hierarchy Level Name
     dataset
  Contact
     Responsible Party
       Organisation Name
         LINZ - Land Information New Zealand
       Position Name
         Lidar Coordination Manager
       Contact Info
         Contact
            Phone
              Telephone
                 Voice
                   04 4600110
            Address
               Address
                 Delivery Point
                   155 The Terrace
                 City
                   Wellington
                 Postal Code
                   6145
                 Country
                   New Zealand
                 Electronic Mail Address
                   info@linz.govt.nz
```

Role

Role Code

Date Stamp
Date

Metadata Standard Name

2020-12-10

ANZLIC Metadata Profile: An Australian/New Zealand Profile of AS/NZS ISO 19115:2005, Geographic information - Metadata

Metadata Standard Version

1.1

Reference System Info
Reference System
Reference System Identifier
Identifier
Code
2193

Identification Info
Data Identification
Citation
Citation
Title

Wellington City LiDAR Index Tiles (2019-2020)

Date

Abstract

This layer contains the Index Tiles for LiDAR data in the Wellington Region including Wellington City as well as the surrounding area captured between 2019 and 2020. - The DEM is available as layer [Wellington City LiDAR 1m DEM (2019-2020)](https://data.linz.govt.nz/layer/105023). - The DSM is available as layer [Wellington City LiDAR 1m DSM (2019-2020)] (https://data.linz.govt.nz/layer/105024). - The LAS point cloud and vendor project reports are available from [OpenTopography](https://portal.opentopography.org/datasets? loc=New%20Zealand). LiDAR was captured for Wellington City Council by Aerial Surveys from 20 March 2019 to 14 March 2020. These datasets were generated by Aerial Surveys and their subcontractors. Data management and distribution is by Land Information New Zealand. Data comprises: - DEM: tif or asc tiles in NZTM2000 projection, tiled into a 1:1,000 tile layout - DSM: tif or asc tiles in NZTM2000 projection, tiled into a 1:1,000 tile layout - Point cloud: las tiles in NZTM2000 projection, tiled into a 1:1,000 tile layout Pulse density specification is at a minimum of 16 pulses/square metre. Vertical datum is NZVD2016.

Status

completed

Point Of Contact Responsible Party Organisation Name

LINZ - Land Information New Zealand

Position Name

Lidar Coordination Manager

Contact Info Contact Phone

```
Telephone
              Voice
                04 4600110
         Address
            Address
              Delivery Point
                155 The Terrace
              City
                Wellington
              Postal Code
                6145
              Country
                New Zealand
              Electronic Mail Address
                info@linz.govt.nz
    Role
       Role Code
         pointOfContact
Resource Maintenance
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    Maintenance And Update Frequency
       Maintenance Frequency Code
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Resource Format
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Descriptive Keywords
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    Type
       Keyword Type Code
         theme
    Thesaurus Name
       Citation
         Title
            ANZLIC Jurisdictions
         Date
         Edition
            Version 2.1
```

Edition Date Date 2008-10-29 Identifier Identifier Code http://asdd.ga.gov.au/asdd/profileinfo/anzlic-jurisdic.xml#anzlic-jurisdic Cited Responsible Party Responsible Party Organisation Name ANZLIC the Spatial Information Council Role Role Code custodian **Resource Constraints** Security Constraints Classification Classification Code unclassified **Resource Constraints Legal Constraints Use Limitation** Copyright of this work is owned by Wellington City Council © Wellington City Council **Use Constraints Restriction Code** copyright **Resource Constraints Legal Constraints Use Limitation** Released by LINZ under Creative Commons Attribution 4.0 New Zealand (CC BY 4.0) with: Following Attribution: "Sourced from the LINZ Data Service and licensed by Wellington City Council, for re-use under CC BY 4.0." For details see: https://www.linz.govt.nz/data/licensingand-using-data/attributing-elevation-or-aerial-imagery-data **Use Constraints Restriction Code** license Spatial Representation Type Code vector Representative Fraction Denominator Integer 1000 Language eng **Character Set** Character Set Code

utf8

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Topic Category Code
       elevation
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            EX _ Geographic Description
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                         Version 1.0
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                         Date
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                              ANZLIC the Spatial Information Council
                            Role
                              Role Code
                                 custodian
                 Code
                    nzl
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Distribution Info
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            Online Resource
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                    https://data.linz.govt.nz/layer/105025-wellington-city-lidar-index-tiles-2019-2020/
Data Quality Info
  DQ _ Data Quality
     Scope
       DQ _ Scope
          Level
            Scope Code
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dataset

Level Description
Scope Description
Other

dataset

Lineage

LI _ Lineage Statement

Data Acquisition: Airborne Laser Scanner (ALS) data was acquired from a fixed wing aircraft from 20 March 2019 to 14 March 2020, using Aerial Surveys Optech Galaxy Prime LiDAR system. Survey Specification: - Scanner: Optech Galaxy Prime - Flying Height: 1300 m AMGL -Scan Angle: ±17 degrees - Scan Frequency: 80Hz - Pulse Rate: 500kHz - Swath Overlap: 55% - Points Per M2: 16 Data Processing: The LiDAR sensor positioning and orientation (POS) was determined using the collected GPS/IMU datasets and Applanix POSPac software. Base Station Positions: PP-RTX The POS data was combined with the LiDAR range files and used to generate LIDAR point clouds in NZTM and ellipsoidal heights. This process was undertaken using Optech LMS LiDAR processing software. The data was checked for completeness of coverage. The relative fit of data in the overlap between strips was also checked. The height accuracy of the ground classified LiDAR points was checked using open land-cover survey check site data collected by Sounds Surveying Ltd. This was done by calculating height differences statistics between a TIN of the LiDAR ground points and the checkpoints. The standard deviation statistic is 0.041m; a RMS of 0.041m and the average difference is -0.001m. LiDAR is relative to the control check points. The positional accuracy of the LiDAR data has been checked by overlaying Sounds Surveying Ltd surveyed data over the LiDAR data displayed coded by intensity. The data was found to fit well in position. The point cloud data was then classified with Terra Solid LiDAR processing software into ground and above ground returns using automated routines tailored to the project landcover and terrain. All product deliverables supplied in terms of NZTM map projection and NZVD2016 vertical datum. Classification of the point cloud followed the classification scheme below: 1 -Unclassified 2 - Ground 3 - Low Vegetation 4 - Medium Vegetation 5 - High Vegetation 6 -Building 7 - Low Noise 9 - Water 14 - Wire Conductor (Major Transmission Lines) 18 - High Noise Lakes and large rivers were hydroflattened in the Bare Earth Digital Elevation Model. The deliverables to LINZ were: 1m gridded bare earth digital elevation model (DEM) 1m gridded digital surface model (DSM) Classified point cloud

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