

Wellington LiDAR 1m DEM (2013)

Metadata

File Identifier

577EC3A1-4336-428C-97E4-E261130D4995

Language

eng

Character Set

Character Set Code

utf8

Hierarchy Level

Scope Code

dataset

Hierarchy Level Name

dataset

Contact

Responsible Party

Organisation Name

LINZ - Land Information New Zealand

Position Name

Lidar Coordination Manager

Contact Info

Contact

Phone

Telephone

Voice

04 4600110

Address

Address

Delivery Point

155 The Terrace

City

Wellington

Postal Code

6145

Country

New Zealand

Electronic Mail Address

info@linz.govt.nz

Role

Role Code

pointOfContact

Date Stamp

Date

2017-06-19

Metadata Standard Name

ANZLIC Metadata Profile: An Australian/New Zealand Profile of AS/NZS ISO 19115:2005,
Geographic information - Metadata

Metadata Standard Version

1.1

Reference System Info

Reference System

Reference System Identifier

Identifier

Code

2193

Identification Info

Data Identification

Citation

Citation

Title

Wellington LiDAR 1m DEM (2013)

Date

Date

Abstract

This layer contains the DEM for LiDAR data from the Wellington region captured in 2013. Note that this DEM is based on automated point cloud classification and contains some residual remnants of surface features. The DSM is available as layer [Wellington LiDAR 1m DSM (2013)](<http://data.linz.govt.nz/layer/3592>). The index tiles are available as layer [Wellington LiDAR Index Tiles (2013)](<http://data.linz.govt.nz/layer/3591>). The LAS point cloud is available from [OpenTopography](<http://opentopo.sdsc.edu/datasets>). Lidar was captured for Greater Wellington Regional Council by Aerial Surveys in 2013. The datasets were generated by Landcare Research. The survey area includes Wellington, Porirua, Lower Hutt, Upper Hutt, Wairarapa, and Kapiti. Data management and distribution is by Land Information New Zealand. Data comprises: •DEM: tif or asc tiles in NZTM2000 projection, tiled into a 1:1,000 tile layout •DSM: tif or asc tiles in NZTM2000 projection, tiled into a 1:1,000 tile layout •Point cloud: las tiles in

NZTM2000 projection, tiled into a 1km x 1km tile layout Data was collected at >1 pulse/square metre pulse density. Attributes include: -Elevation -Intensity values - Return number -Adjusted GPS time -Classification Vertical datum is NZVD2016

Status

Progress Code

completed

Point Of Contact

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Role

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pointOfContact

Resource Format

Format

Name

*.xml

Version

Unknown

Descriptive Keywords

Keywords

Keyword

New Zealand

Type

Keyword Type Code

theme

Thesaurus Name

Citation

Title

ANZLIC Jurisdictions

Date

Edition

Version 2.1

Edition Date

Date

2008-10-29

Identifier

Identifier

Code

<http://asdd.ga.gov.au/asdd/profileinfo/anzlic-jurisdic.xml#anzlic-jurisdic>

Cited Responsible Party

Responsible Party

Organisation Name

ANZLIC the Spatial Information Council

Role

Role Code

custodian

Descriptive Keywords

Keywords

Keyword

LAND-Topography

Keyword

LAND-Cover

Type

Keyword Type Code

theme

Thesaurus Name

Citation

Title

ANZLIC Search Words

Date

Edition

Version 2.1

Edition Date

Date

2008-05-16

Identifier

Identifier

Code

<http://asdd.ga.gov.au/asdd/profileinfo/anzlic-theme.xml#anzlic-theme>

Cited Responsible Party

Responsible Party

Organisation Name

ANZLIC the Spatial Information Council

Role

Role Code

custodian

Resource Constraints

Security Constraints

Classification

Classification Code

unclassified

Resource Constraints

Legal Constraints

Use Limitation

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Spatial Representation Type Code

grid

Representative Fraction

Denominator

Integer

1000

Language

eng

Character Set

Character Set Code

utf8

Topic Category Code

elevation

Topic Category Code

imageryBaseMapsEarthCover

Extent

EX _ Extent

Geographic Element

EX _ Geographic Description

Identifier

Authority

Citation

Title

ANZMet Lite Country codelist

Date

Edition

Version 1.0

Edition Date

Date

2009-03-31

Identifier

Identifier

Code

<http://asdd.ga.gov.au/asdd/profileinfo/anzlic-country.xml#Country>

Cited Responsible Party

Responsible Party

Organisation Name

ANZLIC the Spatial Information Council

Role

Role Code

custodian

Code

nzl

Data Quality Info

DQ _ Data Quality

Scope

DQ _ Scope

Level

Scope Code

dataset

Level Description

Scope Description

Other

dataset

Lineage

LI _ Lineage

Statement

Data Acquisition: Airborne Laser Scanner (ALS) data was acquired from a fixed wing aircraft in 2013 using Aerial Surveys' Optech ALTM 3100EA LiDAR system. Project Scope: Acquisition and delivery of Raw LiDAR Point Cloud Data over the entire Wellington region extending to 100m offshore Acquisition of urban specification (high resolution) LiDAR data: Ground model of +/-0.1 to 0.15m in z (1 sigma) with a resolution of 1.3 points per square metre. Post processing of the LiDAR data with data being delivered in separate flight lines using newly acquired ground control. Survey Specification: Scanner: Optech ALTM 3100EA Flying height: 1000m AMGL Scan Angle: +/- 18.8 degrees Scan Frequency: 53Hz Pulse Rate 100kHz Swath Overlap: 50% Points Per Sqm: 1.73 Data processing: The positional data collected from each flight by the POS-AV510 GPS/IMU system was processed using the Applanix POSMMS application. The ground control survey was carried out by the registered surveyors C&R Surveyors. All product deliverables supplied by Aerial Surveys in terms of NZTM map projection and Wellington 1953 Vertical Datum. The data was converted from NZGD2000 ellipsoidal heights into the local height system using the LINZ NZGeiod09 and Wellington 1953 offset. The point cloud data was classified by Landcare Research per the modified ASPRS classification scheme below, using an automated (Level 1) classification process: 1 - Unassigned 2 - Ground 4 – Vegetation 9 – Water Re-processing: In 2016 the data was reprocessed by Landcare Research for LINZ relative to the NZVD2016 vertical datum, and the DEM and DSM supplied as 1:1000 nominal scale (2500 720m high x 480m wide subtiles per full NZ Topo50 sheet).The deliverables to LINZ were: 1m gridded bare earth digital elevation model (DEM) 1m gridded digital surface model (DSM) Classified point cloud

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